### CHAPTER 1

### TYRES FOR TWO OR THREE-WHEEL MOTOR VEHICLES AND THEIR FITTING

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SHEET $H_1/2$ SHEET $H_1/3$
SHEET Screen projection requirements $H_1/4$
•••••
Appendix 3
Category H <sub>2</sub> lamps
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SHEET $H_2/2$ SHEET $H_2/3$
SHEET Screen projection requirements
H <sub>2</sub> /4
Appendix 4
Category H <sub>3</sub> lamps
SHEET H <sub>3</sub> /1

HEET H <sub>3</sub> /2Definition: Ring centre and reference axis ( <sup>2</sup> )Filament dimensions and tolerances or standard filament lamps, see sheet H <sub>3</sub> /3
HEET H <sub>3</sub> /3 HEET H <sub>3</sub> /4
HEET Screen projection requirements I <sub>3</sub> /5
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HEET Characteristics I <sub>4</sub> /2 HEET H <sub>4</sub> /3
HEET H <sub>4</sub> /4
HEET ADDITIONAL EXPLANATIONS TO SHEETS H <sub>4</sub> /3 AND H <sub>4</sub> /4 I <sub>4</sub> /5
HEET Table of the dimensions referred to in the diagrams on sheets $H_4/3$ and $H_4/4$ (in mm) $H_4/6$ HEET $H_4/7$

Category HS <sub>1</sub>	
SHEET HS <sub>1</sub> /1	
SHEET Characteristics HS <sub>1</sub> /2	
SHEET Table of the dimensions referred to in the diagrams on sheets $HS_1/4$ and $HS_1/5$ (in mn $HS_1/3$	n)
SHEET Position of filaments HS <sub>1</sub> /4	
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SHEET HB <sub>4</sub> /2 SHEET HB <sub>4</sub> /3
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	edure and requirements
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2.1.	

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3.	GENERAL REQUIREMENTS
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4.	TEST METHODS
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<ul><li>4.2.</li><li>5.</li><li>5.1.</li><li>5.2.</li><li>5.2.1.</li></ul>	Test procedure  CRITERIA
4.2. 5. 5.1. 5.2. 5.2.1. 5.2.1.1. 5.2.1.1.	Test procedure  CRITERIA
<ul><li>4.2.</li><li>5.</li><li>5.1.</li><li>5.2.</li><li>5.2.1.</li><li>5.2.1.1.</li></ul>	Test procedure  CRITERIA
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3.	REFLECTING SURFACE AND COEFFICIENTS OF REFLECTION
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2.5.	Testpiece support
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3.2.	Indirect calibration measurements
3.3.	Measurements on a plane rear view mirror
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4.1.1.	Interior rear-view mirror (Class I)
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	CHAPTER 5

MEASURES TO BE TAKEN AGAINST AIR POLLUTION CAUSED BY TWO OR THREE-WHEEL MOTOR VEHICLES

## SPECIFICATIONS FOR MEASURES TO BE TAKEN AGAINST AIR POLLUTION CAUSED BY MOPEDS

1.	DEFINITIONS
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2.	TEST SPECIFICATIONS
2.1.	General
2.2.	<b>Description of tests</b>
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2.2.1.1.	Type I test (average emissions of gaseous pollutants in a congested urban area after cold start)
2.2.1.2.	
2.3.	Diagram and markings
2.3.1.	
2.3.2.	All original equipment catalytic converter(s) shall bear at least the following identifications:
	CONFORMITY OF PRODUCTION
3.	CONFORMITY OF PRODUCTION
3.1.	
<b>3</b> .1.1.	

3.1.1.1.	
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4.	EXTENSION OF THE SCOPE OF THE APPROVAL
4.1.	Vehicle types with different reference masses
4.2.	Vehicle types with different total gear ratios
4.2.1.	
4.2.1.1.	
4.2.2.	
4.2.3.	
4.3.	Vehicle types with different reference masses and different total gear ratios
4.4.	Three-wheel mopeds and light quadricycles
4.5.	
5.	REPLACEMENT CATALYTIC CONVERTERS AND ORIGINAL REPLACEMENT CATALYTIC CONVERTERS
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5.2.1.	Markings

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	Type I test
	(checking the average emission of pollutants in a congested urban area)
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	OPERATING CYCLE ON THE DYNAMOMETER
2.1.	Description of cycle
2.2.	General conditions for carrying out the cycle
2.3.	Use of the gearbox
2.3.1.	
2.3.2.	
2.4.	Tolerances
2.4.1.	

2.4.2.	
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4.	TEST EQUIPMENT
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	Gas-collection equipment
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4.2.	Gas-collection equipment
4.2.	Gas-collection equipment
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4.2. 4.2.4. 4.2.5. 4.2.6.	Gas-collection equipment
4.2. 4.2.4. 4.2.5. 4.2.6.	Gas-collection equipment
4.2. 4.2.4. 4.2.5. 4.2.6. 4.2.7.	Gas-collection equipment
4.2.4. 4.2.4. 4.2.5. 4.2.6. 4.2.7. 4.2.8.	Gas-collection equipment
4.2.4. 4.2.4. 4.2.5. 4.2.6. 4.2.7. 4.2.8. 4.2.9.	Gas-collection equipment
4.2.4. 4.2.4. 4.2.5. 4.2.6. 4.2.7. 4.2.8. 4.2.9. 4.3.	Gas-collection equipment
4.2. 4.2.4. 4.2.5. 4.2.6. 4.2.7. 4.2.8. 4.2.9. 4.3.1.	Gas-collection equipment
4.2. 4.2.4. 4.2.5. 4.2.6. 4.2.7. 4.2.8. 4.2.9. 4.3.1.	Gas-collection equipment

PREPARING THE TEST
Setting of brake
Adjustment of equivalent inertias to the moped's translatory inertias.
Cooling the moped
Conditioning of the test vehicle
The test vehicle shall be moved to the test area and the following operations shall be performed:
The test vehicle shall be moved to the test area and the following operations shall be performed:
The test vehicle shall be moved to the test area and the following operations shall be performed:  Checking of back pressure
The test vehicle shall be moved to the test area and the following operations shall be performed:  Checking of back pressure
The test vehicle shall be moved to the test area and the following operations shall be performed:  Checking of back pressure

6.	PROCEDURE FOR DYNAMOMETER TESTS
6.1.	Special conditions for carrying out the cycle
6.1.1.	
6.1.2.	
6.1.3.	
6.2.	Starting up the engine
6.2.1.	
6.2.2.	
6.2.3.	Idling
6.2.3.1.	
6.2.3.2.	
6.2.4.	Accelerations
6.2.5.	Steady speed
6.2.6.	Decelerations
6.2.6.1.	
6.2.6.2.	
6.2.6.3.	
6.2.6.4.	
7.	PROCEDURE FOR SAMPLING AND ANALYSIS
7.1.	Sampling
7.1.1.	
7.1.2.	
7.1.3.	
7.2.	Analysis
7.2.1.	

7.2.2.	
7.2.3.	
7.2.4.	
7.2.5.	
8.	DETERMINATION OF THE QUANTITY OF GASEOUS POLLUTANTS EMITTED
8.1.	
8.2.	The mass of carbon monoxide gas emitted during the test is determined by means of the formula:
8.3.	
8.4.	The mass of oxides of nitrogen emitted through the moped's exhaust during the test is calculated by means of the formula:
	Carbon dioxide (CO <sub>2</sub> )
8.6.	
9.	

10.	FUEL CONSUMPTION
	Sub-appendix 1
	Operating cycle on dynamometer (Type I test)
	Sub-appendix 2
	Example No 1 of an exhaust-gas collection system
	Sub-appendix 3
	Example No 2 of an exhaust-gas collection system
	Sub-appendix 4
	Method of calibrating the dynamometer
1.	PURPOSE
2.	PRINCIPLE OF THE METHOD
3.	PROCEDURE
3.1.	
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3.3.	
3.4.	

3.5.	
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3.7.	
3.8.	
3.9.	
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	Type II test
	(measuring emissions of carbon monoxide and hydrocarbons at idling speed)
1.	INTRODUCTION
2.	MEASUREMENT CONDITIONS
2.1.	
2.2.	
2.3.	
2.4.	
2.5.	
2.6.	
3.	SAMPLING AND ANALYSIS OF EXHAUST GASES
3.1.	
3.2.	
3.3.	
3.4.	
4.	DETERMINATION OF THE QUANTITY OF GASEOUS POLLUTANTS EMITTED
4.1.	

4.1.1.	
4.1.2.	
4.1.3.	
4.1.3.1.	
4.1.3.2.	
4.1.3.3.	
4.1.4.	
4.1.4.1.	
4.1.4.2.	
4.1.4.3.	
4.1.4.4.	
4.1.4.5.	
4.2.	
4.2.1.	
4.2.2.	
4.2.3.	
4.2.3.1.	
4.2.3.2.	
4.2.3.3.	
4.2.4.	
4.3.	

4.3.1.			
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2.1.			
2.2.			
2.3.			
2.4.			
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1.	DEFINITIONS		
1.1.			
1.1.1.			
1.1.2.			
1.2.			
1.3.			
1.4.			
1.5.			
1.6.			
1.7.			
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1.9.			
1.10.			
2.	TEST SPECIFICATIONS		
2.1.	General		

2.2.	Description of tests
2.2.1.	
2.2.1.1.	
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	2
	.1
	2
2.2.1.2.2	
2.2.1.2.3	
2.2.1.2.4	
2.2.1.2.5	
2.2.1.3.	
2.3.	

2.3.3.	
2.4.	Diagram and markings
2.4.1.	
2.4.2.	All original equipment catalytic converter(s) shall bear at least the following identifications:
3.	CONFORMITY OF PRODUCTION
3.1.	
3.1.1.	
3.1.2.	
4.	EXTENSION OF THE SCOPE OF THE APPROVAL
4.1.	
4.2.	Vehicle types with different total gear ratios
4.2.1.	venicle types with different total geal ratios
4.2.1.1.	
4.2.2.	
4.2.3.	
4.3.	Vehicle types with different reference masses and different total gear ratios

4.4.	Tricycles and quadricycles other than light quadricycles
4.5.	Restriction
5.	REPLACEMENT CATALYTIC CONVERTERS AND ORIGINAL REPLACEMENT CATALYTIC CONVERTERS
5.1.	
5.2.	
5.2.1.	Markings
	Documentation
3.2.2.3.	
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	Type I test (for vehicles tested against the emission limits laid down in Row A of the Table in section 2.2.1.1.5 of this Annex)
	(checking the average emission of pollutants)
1.	INTRODUCTION
 1.1.	
2.	OPERATING CYCLE ON THE DYNAMOMETER
2.1.	Description of cycle

2.2.	General conditions for carrying out the cycle
2.3.	Use of the gearbox
2.3.1.	
2.3.1.1.	
2.3.1.2.	
2.3.1.3.	
2.3.2.	
2.4.	Tolerances
2.4.1.	
2.4.2.	
2.4.3.	
2.4.4. Operatir	ng cycle on the dynamometer
3.	MOTORCYCLE OR MOTOR TRICYCLE AND FUEL
3.1.	Test motorcycle or motor tricycle
3.1.1.	
3.1.2.	
3.1.3.	
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5.3.6.2.	Calculation of power absorption unit force
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5.3.6.3.3	.2n this case, several points are directly input in succession digitally by the data set of $F^*_j$ and $v_j$ , the coastdown is performed and the coastdown time $\Delta t_i$ is measured. By automatic calculation in the following sequence by the built-in CPU, $F_{pau}$ is automatically set in the memory at motorcycle speed intervals of 0,1 km/h, and after the coastdown test is repeated several times, the running resistance setting is computed:
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5.3.6.3.4	.1
5.3.6.3.4	.2n this case, the coefficients $f^*_0$ and $f^*_2$ are directly input digitally; the coastdown is performed and the coastdown time $\Delta t_i$ is measured. The calculation is automatically made in the following sequence by the built-in CPU and $F_{pau}$ is automatically set in the

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8.1.4.2.	
8.1.5.	V is the total volume, expressed in m <sup>3</sup> /test, of diluted gases at reference temperature 0 °C (273 °K) and reference pressure 101,33 kPa,

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8.2.4.	HC <sub>c</sub> is the concentration of the diluted gases expressed in parts per million carbon equivalent (for example: the concentration of propane multiplied by 3) and corrected to take account of the dilution air:
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8.3.4.	$NO_{xc}$ is the concentration of oxides of nitrogen in the diluted gases, expressed in parts per million and corrected to take account of the dilution air:
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8.3.5.	K <sub>h</sub> is the correction factor for humidity:
8.3.5.1.	H is the absolute humidity in grams of water per kg of dry air:
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Operatir	ng cycle of the extra-urban cycle on the dynamometer
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	Type II test
	(measuring emissions of carbon monoxide at idling speed)

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3.1.5.	If the batteries are operated above the ambient temperature, the operator shall follow the procedure recommended by the vehicle manufacturer in order to keep the temperature of the battery in the normal operating range.
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3.2.	Climatic conditions
4.	OPERATION MODES
4.1.	Initial charge of the battery
4.1.1.	Discharge of the battery
4.1.1.1.	For externally chargeable hybrid electric vehicle (OVC HEV) without an operating mode switch, the manufacturer shall provide the means for performing the measurement with the vehicle running in pure electric operating state. The procedure shall start with the discharge of the electrical energy storage device of the vehicle while driving:
4.1.1.2.	For externally chargeable hybrid electric vehicle (OVC HEV) with an operating mode
4.1.2.	Application of a normal overnight charge
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4.1.2.2.	End of charge criteria	
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4.2.1.	To determine the electric range of a hybrid electric vehicle	
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4.2.1.5.	At the end, the measure De of the distance covered using the electrical motor only in km is the electric range of the hybrid electric vehicle. It shall be rounded to the nearest whole number.	
4.2.2.	To determine the OVC range of a hybrid electric vehicle	
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